

1

2

3

4

D

D

C

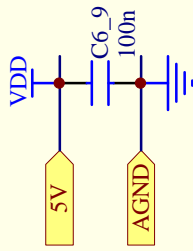
C

B

B

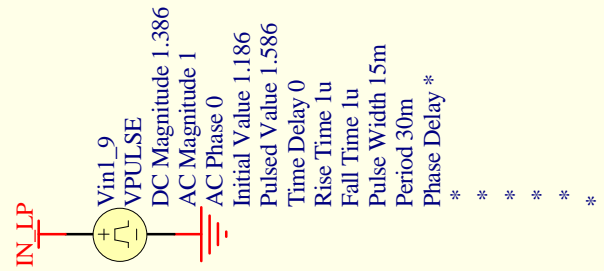
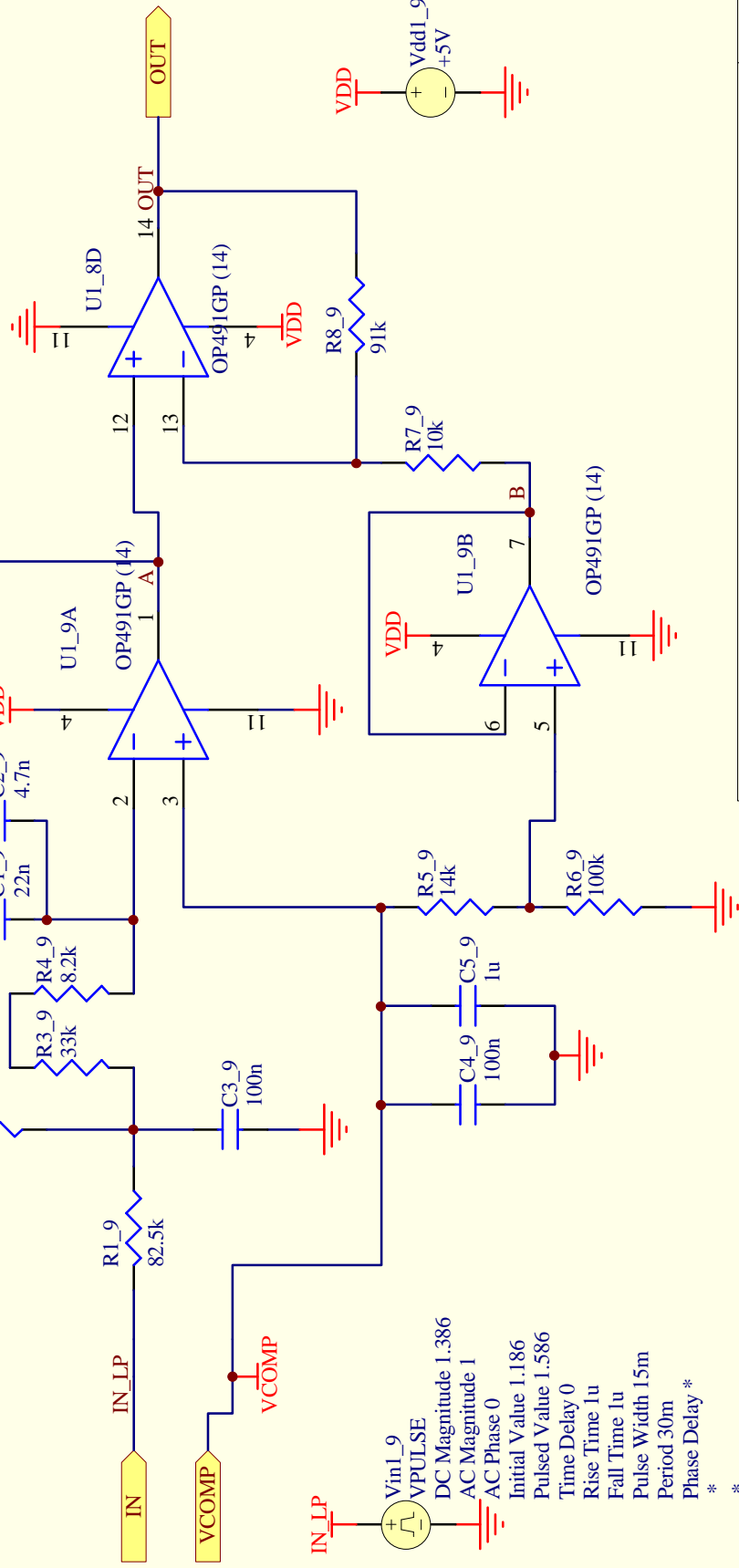
A

A



Multiple Feedback Second Order
Butterworth Low Pass Filter
Fc = 50 Hz
Gain = 1.00

Range Adaption
A = 10



Filter Stage for Gyro ENC03 Y-Axis

Proj Low-Budget Inertial Navigation System
Peter Luethi, Thomas Moser - SS 2000 IFE

Eidgenössische
Technische Hochschule
Zürich

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